### Test runs with different WriteModes

#### What is measured

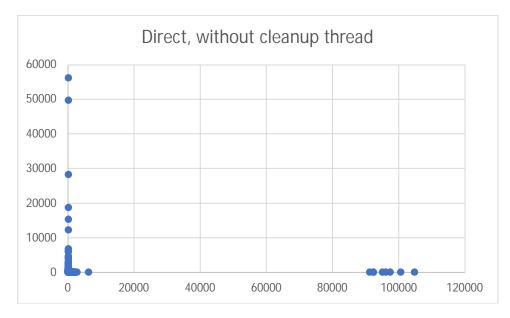
The program initializes the logger, and then writes a huge number of log entries from multiple parallel threads. Each log entry is written with a timestamp that is in all cases created by the application thread. The diagrams show how often a certain time interval between consecutive log entries from the same thread occurred.

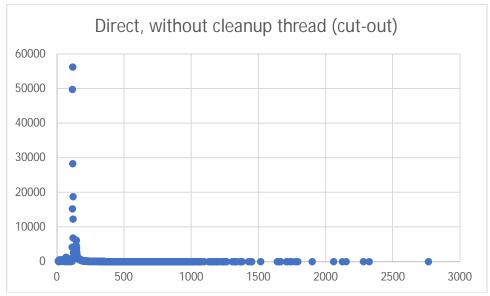
No measures were taken to "silence" the rest of the machine.

The x-axis is in nanoseconds in all diagrams.

## WriteMode::Direct, without cleanup thread: Peak at about 120ns, outliers at 100ms

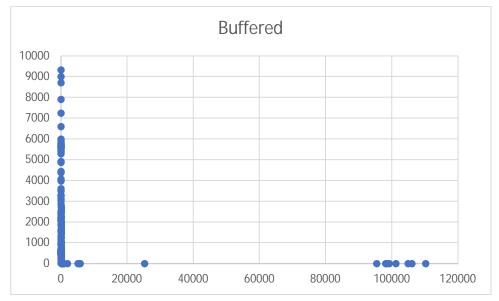
- Direct writing causes file I/O with every log message
- Outliers are caused by file rotation and cleanup.

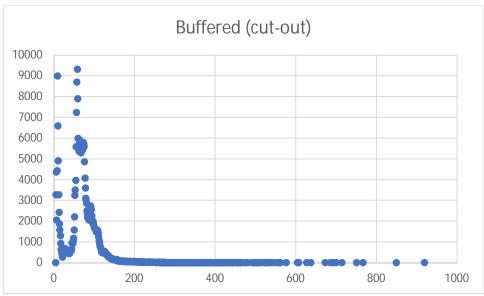




# WriteMode::Buffered, without cleanup thread: Peak below 80ns, outliers at 100ms

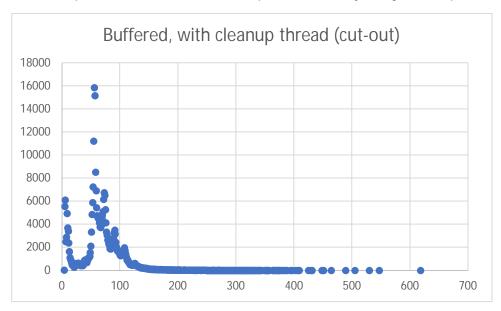
- Buffered writing reduces file I/O
- · Outliers are caused by file rotation and cleanup





# WriteMode::Buffered, with cleanup thread: Peak below 80ns, outliers at 4-7ms

· Impact of file rotation and cleanup is minimized by doing it in a separate thread



### WriteMode::Async:

### Peaks at below 10 and below 50ns, very flat tail, no outliers

- A separate thread is doing all (buffered) file I/O, and the cleanup
- Impact of logging on application threads is minimized, pushback hardly recognizable
- Additional dependency to crossbeam

